Selecting a Lens for your Camera

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Applicable Products

- All FLIR machine vision cameras

Application Note Description

This application note explains the following important factors to consider when selecting a lens for your imaging camera:

- Lens mount
- Lens focal length
- Sensor size
- Sensor spatial resolution

Camera Lens Mount

You must select a lens that is compatible with the lens mount of the camera. Most FLIR machine vision cameras are equipped with either a C- or CS-mount. We also provide 5 mm C-to-CS-mount spacers, M12 lens mounts and CS-to-M12 adapters.

Flange Back Distance on C- and CS-mount Cameras

C- and CS-mount lenses are both threaded lens mounts found on most industrial CCD cameras and lenses. The difference between C and CS-mount equipment is the distance between the flange of the lens (the part of the case that butts up against the camera) and the focal plane of the lens (where the CCD sensor must be positioned). This is known as the flange back distance.
The C-mount lens specification for flange back distance is 17.53 mm, and on CS-mount lenses it is 12.53 mm. However, on FLIR machine vision cameras, these physical distances are offset due to the presence of both a 1 mm infrared cutoff (IRC) filter and a 0.5 mm sensor package window. These two pieces of glass fit between the lens and the sensor image plane. The IRC filter is installed by us on color cameras; in monochrome cameras, the IRC is replaced with a transparent glass window. The sensor package window is installed by the sensor manufacturer. The refraction of these glass components requires an offset in the flange back distance from the nominal values.

If you have a CS-mount camera and a C-mount lens, you can add a 5mm spacer to obtain the correct focus. If, however, you have a C-mount camera and a CS-mount lens, correct focus cannot be achieved.

**Compatibility with M12 Microlenses**

M12 (sometimes referred to as S-mount) optics are often a popular alternative to C- or CS-mount optics due to their smaller size and lower cost. FLIR offers a variety of M12-based products, including lens mounts (plastic or metal), lenses, a CS-to-M12 adapter, and some cameras with M12 lens mount pre-installed.

Our cast metal M12 lens holder is made of zinc alloy and is designed to fit larger format sensors such as the Sony ICX445 CCD and the Sony IMX035 CMOS. Additional features include a set screw for adjusting back focal distance, dowel pins for precise alignment of the lens holder to the camera circuit board, and an IRC filter.

We also have available a CS-to-M12 lens adapter, which is useful for attaching M12 lenses to a camera equipped with a CS-mount lens holder.

There may be some compatibility issues with particular wide angle (short focal length) M12 lenses. Compatibility issues are primarily a result of back focal length differences, as explained below.
The distance required for the lens to be in focus is greater than the length of the lens holder, requiring the lens to be unattached from the holder in order for it to be focused.

The distance required for the lens to be in focus is less than the length of the lens holder. The image is still unfocused even with the lens screwed all the way into the lens holder.

The microlens may encounter the IR filter before being able to come into focus.

The microlens may be in focus, but is too short to be fixed in place by the lens set screw.
**Lens Focal Length**

Another important consideration when selecting a lens is its focal length. A lens with a focal length approximately equal to the diagonal size of the sensor format reproduces a perspective that generally appears normal to the human eye. Lenses with shorter than normal focal lengths, also called ‘wide angle’ lenses, can capture a larger field of view. Lenses with longer than normal focal lengths, or ‘telephoto’ lenses, capture a smaller field of view. Therefore, when considering focal length, you must consider the sensor size, the field of view you want to capture, and approximately how far from your subject the lens is located, also known as the ‘working distance.’

The focal point is the position on the optical axis where all incoming rays that are parallel to the optical axis intersect. Focus is achieved when all rays originating from the same point on the scene refract so that they intersect at exactly the same point on the image plane. This concept is illustrated in the diagram below. Note that with a symmetric lens, focal points F and F’ are equidistant from the lens. A ray that passes through F refracts so that it is parallel to the optical axis before it hits the image plane.

The relationship between the focal length, the working distance and the image distance is given by the Gaussian lens formula:

\[
\frac{1}{\text{focal length}} = \frac{1}{\text{working dist}} + \frac{1}{\text{image dist}}
\]

In many imaging applications, the working distance is considerably larger than the image distance. In this case, we can approximate the above equation as:

\[
\frac{1}{\text{focal length}} \approx \frac{1}{\text{image dist}}
\]

We see that the image distance is approximately equal to the focal length. A simplified ray diagram for this case is shown below where only the chief rays from the sensor edges are drawn. These rays pass through the center of the lens without a change in direction.
The approximate value of the focal length in this case is given by:

\[
focal\_length \approx \frac{\text{sensor\_size} \times \text{working\_dist.}}{\text{field\_of\_view}}
\]

For close-up applications such as macro photography, where the working distance is not significantly larger than the focal length, we cannot approximate the image distance to be the focal length. The more accurate form of the above equation (applicable both for near and far working distances) is given by:

\[
focal\_length = \frac{\text{sensor\_size} \times \text{working\_dist.}}{\text{field\_of\_view} + \text{sensor\_size}}
\]

Many lens vendors provide lens selection calculators on their websites that produce a recommended focal length based on the approximate form of the focal length equation. If in doubt, the calculation is straightforward and can be done manually with knowledge of the sensor dimensions. The sensor size is typically given in fractional units of an inch which, for historic reasons, can’t be directly scaled into the actual size of the effective imaging area of the sensor. The table below gives a list of the widths, heights, and diagonals of several standard sensor sizes.

For example, consider an application using a 1/2” sensor, a working distance of 100 mm, and a horizontal field of view of 50 mm. Looking at the table, the 1/2” sensor has a width of 6.4 mm, a height of 4.8 mm, and a diagonal of 8 mm. To achieve the specified horizontal field of view, we use:

\[
focal\_length \approx \frac{6.4 \times 100}{50} = 12.8\text{mm}
\]

or using the exact equation:

\[
focal\_length = \frac{6.4 \times 100}{50 + 6.4} = 11.3\text{mm}
\]

The result is a focal length of 11.3 mm using the exact formula and 12.8 mm using the approximate formula. This discrepancy increases as the working distance decreases relative to the focal length.
Once you choose a focal length that best meets your requirements, you may need to adjust your working distance to achieve the desired field of view. Also, keep in mind that lenses with shorter focal lengths often exhibit pronounced distortion. The actual amount of distortion depends on the specific lens being used and can have a considerable impact on the actual field of view. The above equations ignore distortion. If the lens distortion is large (for example > 10%), the above equations are inaccurate for predicting the focal length and should only be used as starting point. The datasheet for the lens should be consulted. Typically an angular field of view is specified for wide angle and fish-eye lenses for each sensor format that is supported by the lens. This angular field of view should be used to calculate the working distance for a given field of view in units of distance.

**Sensor Size**

When purchasing a lens, make sure it is compatible with the optical size of the image sensor (for example, 1/3", 2/3", and so on) used in your camera. The lens must be able to project an image that covers the whole sensor. A lens made for a larger format sensor, such as 2/3", can usually be used with a smaller format sensor, such as 1/3", although there may be a loss of resolution (see below). However, the apparent focal length seems larger by the same factor as the sensor is smaller. The effect is comparable to applying a centered region of interest on a larger sensor. A lens made for a smaller sensor, such as 1/3”, cannot be used with a larger sensor, such as 1/2”, because the lens most likely does not project a large enough image to cover the whole sensor. The image corners in this case may appear blurry, dark (vignette), or even completely black.

The following table shows the approximate width (W), height (H), and diagonal (D) of the active area for different sized sensors, and the crop factors associated with using a certain lens on a smaller sensor. For example, suppose we have a 6 mm lens paired with a 1/3” sensor and you want to know what lens achieves the same field of view on a 1/4” sensor. The crop factor of the 1/3” sensor relative to the 1/4” sensor is 1.33. Therefore you select a focal length of 6 mm / 1.33 = 4.5 mm.

<table>
<thead>
<tr>
<th>Sensor Size</th>
<th>Dimensions in mm</th>
<th>Crop factor using a lens made for...</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>W</td>
<td>H</td>
</tr>
<tr>
<td>1/4&quot;</td>
<td>3.6</td>
<td>2.7</td>
</tr>
<tr>
<td>1/3&quot;</td>
<td>4.8</td>
<td>3.6</td>
</tr>
<tr>
<td>1/2&quot;</td>
<td>6.4</td>
<td>4.8</td>
</tr>
<tr>
<td>1/1.8&quot;</td>
<td>7.1</td>
<td>5.4</td>
</tr>
<tr>
<td>2/3&quot;</td>
<td>8.8</td>
<td>6.6</td>
</tr>
<tr>
<td>1&quot;</td>
<td>12.8</td>
<td>9.6</td>
</tr>
</tbody>
</table>
Sensor Spatial Resolution and Megapixel Lenses

Another important factor when selecting a lens is the number of pixels relative to the total sensor area. This measurement is usually inversely proportional to the pixel (unit cell) size—the higher the number of pixels, the smaller the individual pixels and the closer together they are. In turn, the smaller the pixel spacing on a sensor, the better its ability to record (sample) small detail. This ability is referred to as spatial frequency or spatial resolution. High density sensors require megapixel (MP) lenses built with higher quality optical components that can project images at a resolution equal to or higher than that of the sensor.

The table below shows a sample of sensors used in FLIR cameras and whether an MP lens should be used with them. It is advisable to use an MP lens with a megapixel sensor. For multi-megapixel sensors, the MP rating of the lens should meet or exceed the MP number of the sensor. Using a regular lens on a megapixel sensor may result in blurred images since the lens may not provide a high enough resolution for the sensor. Although it is acceptable to use an MP lens with a non-megapixel sensor, it may be impractical from a cost-benefit perspective.

<table>
<thead>
<tr>
<th>Sensor</th>
<th>Size</th>
<th>Width (pixels)</th>
<th>Height (pixels)</th>
<th># of Pixels (MP)</th>
<th>Pixel Size (square μm)</th>
<th>lpm</th>
<th>Megapixel Lens Required?</th>
</tr>
</thead>
<tbody>
<tr>
<td>ICX618</td>
<td>1/4”</td>
<td>648</td>
<td>488</td>
<td>0.3</td>
<td>5.6</td>
<td>89</td>
<td>No</td>
</tr>
<tr>
<td>ICX424</td>
<td>1/3”</td>
<td>648</td>
<td>488</td>
<td>0.3</td>
<td>7.4</td>
<td>68</td>
<td>No</td>
</tr>
<tr>
<td>ICX414</td>
<td>1/2”</td>
<td>648</td>
<td>488</td>
<td>0.3</td>
<td>9.9</td>
<td>51</td>
<td>No</td>
</tr>
<tr>
<td>ICX204</td>
<td>1/3”</td>
<td>1032</td>
<td>776</td>
<td>0.8</td>
<td>4.65</td>
<td>108</td>
<td>1 MP recommended</td>
</tr>
<tr>
<td>ICX445</td>
<td>1/3”</td>
<td>1296</td>
<td>964</td>
<td>1.3</td>
<td>3.75</td>
<td>133</td>
<td>1 MP recommended</td>
</tr>
<tr>
<td>ICX267</td>
<td>1/2”</td>
<td>1392</td>
<td>1032</td>
<td>1.4</td>
<td>4.65</td>
<td>108</td>
<td>1 MP recommended</td>
</tr>
<tr>
<td>ICX274</td>
<td>1/1.8”</td>
<td>1624</td>
<td>1224</td>
<td>2.0</td>
<td>4.4</td>
<td>114</td>
<td>2 MP recommended</td>
</tr>
<tr>
<td>ICX655</td>
<td>2/3”</td>
<td>2448</td>
<td>2048</td>
<td>5.0</td>
<td>3.45</td>
<td>145</td>
<td>5 MP recommended</td>
</tr>
<tr>
<td>IMX250</td>
<td>2/3”</td>
<td>2448</td>
<td>2048</td>
<td>5.0</td>
<td>3.45</td>
<td>145</td>
<td>5 MP recommended</td>
</tr>
<tr>
<td>ICX694</td>
<td>1”</td>
<td>2736</td>
<td>2192</td>
<td>6.0</td>
<td>4.54</td>
<td>110</td>
<td>5 MP recommended</td>
</tr>
<tr>
<td>IMX255</td>
<td>1”</td>
<td>4096</td>
<td>2160</td>
<td>8.9</td>
<td>3.45</td>
<td>145</td>
<td>12 MP recommended</td>
</tr>
<tr>
<td>IMX172</td>
<td>1/2.3”</td>
<td>4000</td>
<td>3000</td>
<td>12.0</td>
<td>1.55</td>
<td>323</td>
<td>12 MP recommended</td>
</tr>
<tr>
<td>IMX253</td>
<td>1.1”</td>
<td>4096</td>
<td>3000</td>
<td>12.3</td>
<td>3.45</td>
<td>145</td>
<td>12 MP recommended</td>
</tr>
<tr>
<td>IMX183</td>
<td>1”</td>
<td>5472</td>
<td>3648</td>
<td>20.0</td>
<td>2.4</td>
<td>208</td>
<td>12 MP recommended</td>
</tr>
</tbody>
</table>

Ideally, the lens format should also be matched to the sensor format for best performance. For example, a 1 MP 2/3” format lens on a 1 MP 1/3” sensor likely underperforms in resolution because the sensor is only capturing a fraction of the total detail produced by the lens. The 1 MP 1/3” lens, because of the smaller sensor area, provides a higher resolution than a 1 MP 2/3” in order to capture the same 1 MP worth of image content. Sensor spatial resolution is measured in line-pairs per millimeter (lpm or lp/mm), which denotes the smallest size of repeated pairs of black/white bars a sensor can resolve. A 1/3” 1.3 MP sensor, such as the Sony ICX445 with a pixel size of...
just 3.75 micrometers, can resolve ~133 lpm (1/3.75 µm x 1/2 x 1000 µm/mm). MP lenses can project images at
greater detail to make use of the higher pixel density of small format megapixel sensors like the Sony ICX445 (1/3”
1.3 MP) or Sony ICX655 (2/3” 5 MP).

The resolution of a lens is typically measured by imaging sets of black and white bars with different pitches (lpm).
The finest pitch (at the sensor) that can be just resolved is considered the resolution of the lens. This resolution is
then multiplied by 2 (to convert line pairs to lines) and then multiplied by the dimensions of the sensor size to
determine the MP rating for the lens. There are a few pitfalls with this sort of measurement. Firstly, the resolution of
the lens varies across the field of view (typically highest near the image center) and so the details of where the
resolution is measured have a large impact on the MP rating. A second pitfall lies in the perception of “just
resolved” as it may differ from one tester to another. Furthermore, two lenses may just resolve 133 lpm and so
have the same MP rating, but this does not ensure they provide the same contrast at for example 60 lpm. The MP
rating therefore does not always tell the whole story.

A more systematic measure of lens resolution is the Modulation Transfer Function (MTF). The MTF measures the
amplitude (contrast) of an image of a sinusoidal pattern\(^1\) that smoothly cycles between black and white at a given
spatial frequency in cycles/mm (cy/mm though sometimes called lp/mm or lpm). The higher the spatial frequency
of such a pattern, the more likely the image blurs into a uniform gray. The nominal “resolution” from this
measurement is then the frequency at which the contrast drops to some percentage of the low frequency
contrast, analogous to the bandwidth of an electrical circuit. This is typically expressed as MTF50 (50% of the low
frequency contrast) or MTF30 (30% of the low frequency contrast). MTF10 is also sometimes used and has an
approximate equivalence to the “just resolved” resolution obtained from bar patterns (see above). Caution should
be used with MTF10 as it is difficult to reliably measure. Another metric is to measure the contrast for a limited set
of specific frequencies, often shown as a function of the radial position in the image. While MTF data can provide
much more detailed information about the lens quality compared to a simple MP rating, the interpretation is more
complicated and the data may not always be available.

### Other Resources

<table>
<thead>
<tr>
<th>Description</th>
<th>Link</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lens holders, adapters and spacers offered by FLIR</td>
<td>Product Accessories</td>
</tr>
<tr>
<td>Lens calculator</td>
<td>Lens Calculator</td>
</tr>
<tr>
<td>Additional information about lens resolution and MTF</td>
<td><a href="http://www.cambridgeincolour.com/tutorials/lens-quality-mtf-resolution.htm">http://www.cambridgeincolour.com/tutorials/lens-quality-mtf-resolution.htm</a></td>
</tr>
</tbody>
</table>

### Downloads and Support

FLIR endeavors to provide the highest level of technical support possible to our customers. Most support
resources can be accessed through the Support section of our website.

\(^1\)MTF measurements can also be performed by other methods such as point spread and slanted edge analysis.
The first step in accessing our technical support resources is to obtain a Customer Login Account. This requires a valid name and email address. To apply for a Customer Login Account go to our Downloads page.

Customers with a Customer Login Account can access the latest software and firmware for their cameras from our website. We encourage our customers to keep their software and firmware up-to-date by downloading and installing the latest versions.

Finding Information

**FlyCapture SDK**—The FlyCapture SDK provides API examples and the FlyCap camera evaluation application. Available from our Downloads page.

**API Documentation**—The installation of the FlyCapture SDK comes with API references for C++, C#, and C code. Available from Start Menu→All Programs→Point Grey FlyCapture2 SDK→Documentation

**Product Documentation**—The camera’s *Getting Started Manual* provides information on installing components and software needed to run the camera. The *Technical Reference* provides information on the camera’s specifications, features and operations, as well as imaging and acquisition controls. They are available from the Downloads page.

**Knowledge Base**—A database of articles and application notes with answers to common questions as well as articles and tutorials about hardware and software systems. Available from our Knowledge Base.

**Learning Center**—Our Learning Center contains links to many resources including videos, case studies, popular topics, other application notes, and information on sensor technology.

Contacting Technical Support

Before contacting Technical Support, have you:

1. Read the product documentation?
2. Searched the Knowledge Base?
3. Downloaded and installed the latest version of software and/or firmware?

If you have done all the above and still can’t find an answer to your question, contact our Technical Support team.